Abstract

The present invention provides a method for deciding on the triggering of and controlling restraint systems (5, 6, 7) of a motor vehicle (1), including the method steps of determining the current position of the motor vehicle (1); determining position-relevant environmental data of the motor vehicle (1); determining position-relevant reference values of the motor vehicle (1); determining position-relevant actual values of the motor vehicle (1); comparing the reference and actual values; and taking this data into account in the decision to trigger, and in the triggering of restraint systems (5, 6, 7). The present invention also provides a device for this purpose.

(Figure 2)

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